Fire Fighting robot

Introduction:

According to National Crime Records Bureau (NCRB), it is estimated that more than 1.2 lakh deaths have been caused because of fire accidents in India from 2010-2014. Even though there are a lot of precautions taken for Fire accidents, these natural/man-made disasters do occur now and then. In the event of a fire breakout, to rescue people and to put out the fire we are forced to use human resources which are not safe. With the advancement of technology especially in robotic it is very much possible to replace humans with robots for fighting the fire. This would improve the efficiency of firefighters and would also prevent them from risking human lives. Today we are going to build a Fire Fighting Robot using Arduino, which will automatically sense the fire and start the water pump

In this project, we build a simple robot using Arduino that could move towards the fire and pump out water around it to put down the fire. It is a very simple robot that would teach us the underlying concept of robotics.

Material Required:

- Arduino UNO
- Fire sensor or Flame sensor
- Servo Motor (SG90)
- L293D motor Driver module
- Mini DC Submersible Pump

- Small Breadboard
- Robot chassis with motors and wheels
- Connecting wires

Working principle:

The main brain of this project is the Arduino. As these sensors have an IR Receiver (Photodiode) which is used to detect the fire. How is this possible? When fire burns it emits a small amount of Infra-red light, this light will be received by the IR receiver on the sensor module. Then by using an Op-Amp to check for change in voltage across the IR Receiver, so that if a fire is detected the output pin (DO) will give 0V(LOW) and if the is no fire the output pin will be 5V(HIGH).

So, by placing three such sensors in three directions of the robot to sense on which direction the fire is burning.



We detect the direction of the fire we can use the motors to move near the fire by driving our motors through the L293D module. When near a fire we have to put it out using water. Using a small container we can carry water, a 5V pump is also placed in the container and the whole container is placed on top of a servo motor so that we can control the direction in which the water has to be sprayed.